

(Quasi-)Monte Carlo Importance Sampling with QMCPy

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(Q)MC Math

Applications in applied statistics, finance, computer graphics, ...

$$\mu = \int_{\mathcal{T}} g(\mathbf{t}) \lambda(\mathbf{t}) d\mathbf{t} = \int_{[0,1]^d} g(\Psi(\mathbf{x})) \lambda(\Psi(\mathbf{x})) |\Psi'(\mathbf{x})| d\mathbf{x} = \int_{[0,1]^d} f(\mathbf{x}) d\mathbf{x} = \mathbb{E}[f(\mathbf{X})]$$
$$\mathbf{X} \sim \mathcal{U}[0,1]^d$$

Original Integrand $g : \mathcal{T} \rightarrow \mathbb{R}$

True Measure $\lambda : \mathcal{T} \rightarrow \mathbb{R}^+$ e.g. probability density or 1 for Lebesgue measure

Transformation $\Psi : [0,1]^d \rightarrow \mathcal{T}$ with Jacobian $|\Psi'(\mathbf{x})|$

Transformed Integrand $f : [0,1]^d \rightarrow \mathbb{R}$

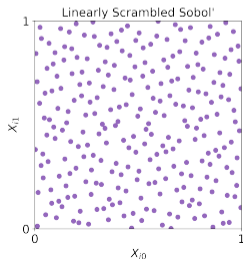
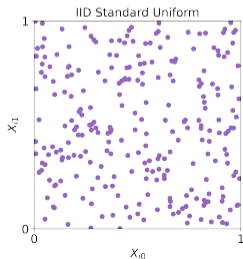
(Q)MC Approximation

$$\text{sample mean} = \hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n f(\mathbf{x}_i) \approx \int_{[0,1]^d} f(\mathbf{x}) d\mathbf{x} = \mu = \text{mean}$$

Discrete Distribution: $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n \sim \mathcal{U}[0, 1]^d$

Monte Carlo: $\{\mathbf{x}_i\}_{i=1}^n$ IID (Independent Identically Distributed)

Quasi-Monte Carlo: $\{\mathbf{x}_i\}_{i=1}^n$ LD (Low-Discrepancy)



Standard Keister Example [1]

$$\begin{aligned}\mu &= \int_{\mathbb{R}^d} \cos(\|\mathbf{t}\|) \exp(-\|\mathbf{t}\|^2) d\mathbf{t} \\ &= \int_{\mathbb{R}^d} \underbrace{\pi^{d/2} \cos(\|\mathbf{t}\|)}_{g(\mathbf{t})} \underbrace{\pi^{-d/2} \exp(-\|\mathbf{t}\|^2)}_{\lambda(\mathbf{t})=\mathcal{N}(\mathbf{t}|\mathbf{0},1/2)} d\mathbf{t} \\ &= \int_{[0,1]^d} \pi^{d/2} \cos(\|\Psi(\mathbf{x})\|) d\mathbf{x} \\ &= \int_{[0,1]^d} \underbrace{g(\Psi(\mathbf{x}))}_{f(\mathbf{x})} d\mathbf{x}\end{aligned}$$

Where $\Psi(\mathbf{x}) = \Phi^{-1}(\mathbf{x})/\sqrt{2}$ and Φ is the standard normal CDF.

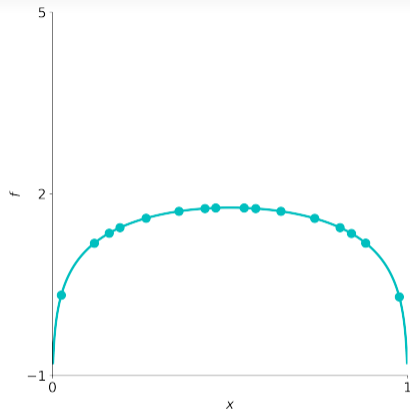
Chose Ψ so $\lambda(\Psi(\mathbf{x}))|\Psi'(\mathbf{x})| = 1$ and $f(\mathbf{x}) = g(\Psi(\mathbf{x}))$, weight and Jacobian cancel

Import QMCPy [2] and NumPy [3]

```
>>> import qmcpy as qp
>>> import numpy as np
```

Sample the Standard Keister

```
>>> sobol = qp.Sobol(dimension=3, seed=11)
>>> keister = qp.Keister(sobol)
>>> x = sobol.gen_samples(2**4)
>>> y = keister.f(x)
```

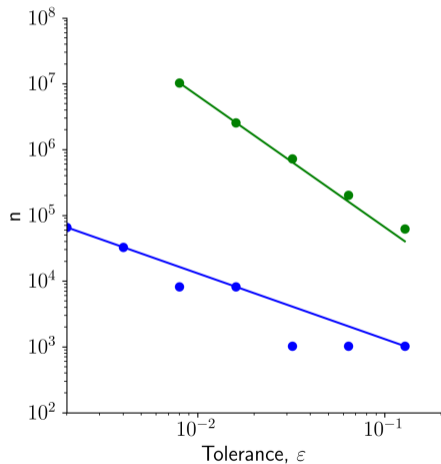
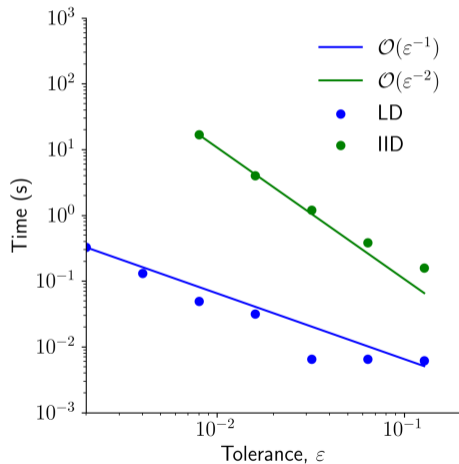


Numerical integration based on CubQMCSobolG [4] stopping criterion

```
>>> stop_obj = qp.CubQMCSobolG(keister, abs_tol=5e-6)
>>> solution, data = stop_obj.integrate()
```

```
>>> data # print(data)
Solution: 2.1683
Keister (Integrand Object)
Sobol (DiscreteDistribution Object)
    d                3
    randomize        1
    seed              11
    mimics            StdUniform
Gaussian (TrueMeasure Object)
    mean              0
    covariance        2(-1)
CubQMCSobolG (StoppingCriterion Object)
    abs_tol           5.00e-06
    rel_tol           0
LDTransformData (AccumulateData Object)
    n_total           2(22)
    solution          2.168
    error_bound       3.36e-06
    time_integrate    3.769
```

Standard Keister Integrand in 5 Dimensions



(Q)MC with Importance Sampling (IS)

Standard (Q)MC: select Ψ so that $\lambda(\Psi(\mathbf{x}))|\Psi'(\mathbf{x})| = 1$

(Q)MC with IS: select Ψ_{IS} so that $\lambda_{\text{IS}}(\Psi_{\text{IS}}(\mathbf{x}))|\Psi'_{\text{IS}}(\mathbf{x})| = 1$

$$\begin{aligned}\mu &= \int_{\mathcal{T}} g(\mathbf{t})\lambda(\mathbf{t}) \, d\mathbf{t} = \int_{[0,1]^d} g(\Psi_{\text{IS}}(\mathbf{x}))\lambda(\Psi_{\text{IS}}(\mathbf{x}))|\Psi'_{\text{IS}}(\mathbf{x})| \, d\mathbf{x} \\ &= \int_{[0,1]^d} g(\Psi_{\text{IS}}(\mathbf{x})) \underbrace{\frac{\lambda(\Psi_{\text{IS}}(\mathbf{x}))}{\lambda_{\text{IS}}(\Psi_{\text{IS}}(\mathbf{x}))}}_{f_{\text{IS}}(\mathbf{x})} \, d\mathbf{x}\end{aligned}$$

Select $\lambda_{\text{IS}} : \mathcal{T} \rightarrow \mathbb{R}^+$ so that $\text{Var}(f_{\text{IS}})$ is small.

More expensive to evaluate f_{IS} than $f(\mathbf{x}) = g(\Psi(\mathbf{x}))$

Gaussian Keister IS Example

$$\mu = \int_{\mathbb{R}^d} \underbrace{\pi^{d/2} \cos(\|\mathbf{t}\|)}_{g(\mathbf{t})} \underbrace{\pi^{-d/2} \exp(-\|\mathbf{t}\|^2)}_{\lambda(\mathbf{t})} d\mathbf{t}$$

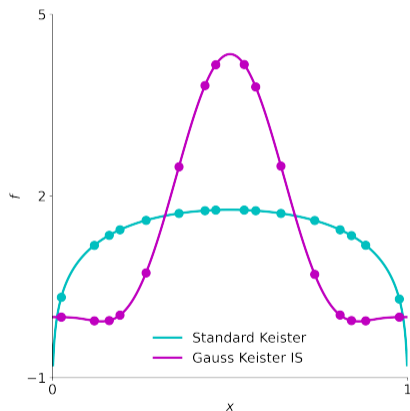
Suppose we choose Ψ_{IS} so $\lambda_{\text{IS}}(\mathbf{t}) = \mathcal{N}(\mathbf{t}|\boldsymbol{\mu}, \Sigma)$ and $\lambda_{\text{IS}}(\Psi_{\text{IS}}(\mathbf{x}))|\Psi'_{\text{IS}}(\mathbf{x})| = 1$

$$\begin{aligned} \mu &= \int_{[0,1]^d} \pi^{d/2} \cos(\|\Psi_{\text{IS}}(\mathbf{x})\|) \mathcal{N}(\Psi_{\text{IS}}(\mathbf{x})|\mathbf{0}, I/2) |\Psi'_{\text{IS}}(\mathbf{x})| d\mathbf{x} \\ &= \int_{[0,1]^d} \pi^{d/2} \cos(\|\Psi_{\text{IS}}(\mathbf{x})\|) \frac{\mathcal{N}(\Psi_{\text{IS}}(\mathbf{x})|\mathbf{0}, I/2)}{\mathcal{N}(\Psi_{\text{IS}}(\mathbf{x})|\boldsymbol{\mu}, \Sigma)} d\mathbf{x} \end{aligned}$$

If $\lambda_{\text{IS}}(\mathbf{t}) = \mathcal{N}(\mathbf{t}|\mathbf{0}, I/2)$, then we recover $f_{\text{IS}}(\mathbf{x}) = f(\mathbf{x}) = \pi^{d/2} \cos(\|\Psi_{\text{IS}}(\mathbf{x})\|)$

Keister Integrand Importance Sampled by $\lambda_{IS}(t) = \mathcal{N}(t|0, 3I)$

```
>>> sobol = qp.Sobol(dimension=3, seed=11)
>>> transform = qp.Gaussian(sobol,
...     mean = 0,
...     covariance = 3)
>>> keister_gauss = qp.Keister(transform)
>>> stop_obj = qp.CubQMCSobolG(
...     integrand = keister_gauss,
...     abs_tol = 5e-6)
>>> solution, data = stop_obj.integrate()
```



Took 70% the time and 50% the samples compared to standard Keister

```
>>> data
Solution: 2.1683
Gaussian (TrueMeasure Object)
  mean          0
  covariance     2(-1)
  decomp_type   pca
  transform     Gaussian (TrueMeasure Object)
                    mean          0
                    covariance     3
                    decomp_type   pca
LDTransformData (AccumulateData Object)
  n_total       2(21)
  solution      2.168
  error_bound   2.47e-06
  time_integrate 2.635
```

Asian Option Example

Time Horizon τ ; Interest Rate r ; Volatility σ ; Start Price S_0 ; Strike Price K

True Measure

$$\mathbf{T} = (T_1, \dots, T_d) \sim \mathcal{N}(\mathbf{0}, \Sigma) \quad \text{for} \quad \Sigma = (\tau/d)(\min(k, j))_{j,k=1}^d$$

Asset Path

$$S_j(\mathbf{T}) = S_0 \exp((r - \sigma^2/2)\tau j/d + \sigma T_j) \quad \text{for} \quad j = 1, \dots, d$$

Payoff

$$\text{Pay}(\mathbf{S}) = \max \left(\frac{1}{2d} \sum_{j=1}^d (S_{j-1} + S_j) - K, 0 \right) \quad \text{for} \quad \mathbf{S} = (S_0, \dots, S_d)$$

Expected Discounted Payoff

$$\mu = \mathbb{E}(g(\mathbf{T})) = \int_{\mathbb{R}^d} g(\mathbf{t}) \mathcal{N}(\mathbf{t}|\mathbf{0}, \Sigma) d\mathbf{t} \quad \text{for} \quad g(\mathbf{t}) = \text{Pay}(\mathbf{S}(\mathbf{t})) \exp(-r\tau)$$

Standard (Q)MC: Choose Ψ so that $\lambda(\Psi(\mathbf{x}))|\Psi'(\mathbf{x})| = 1$

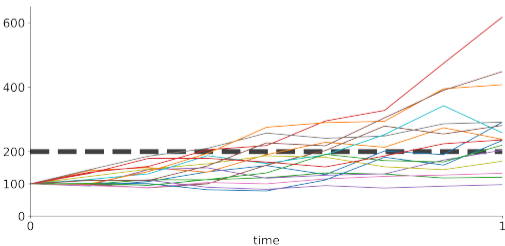
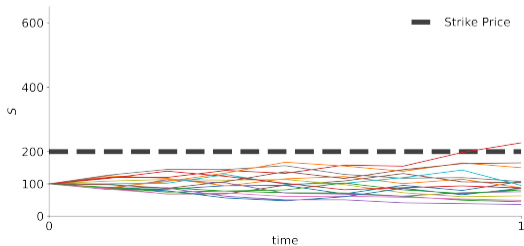
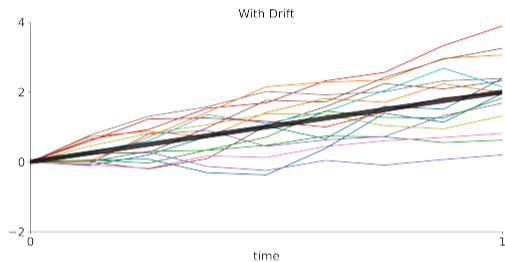
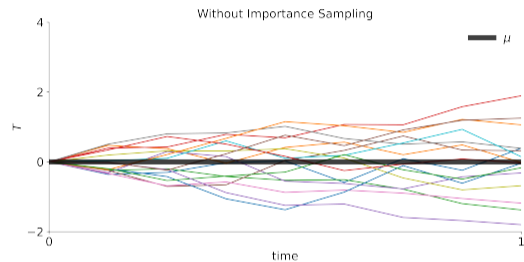
$$\mu = \int_{\mathbb{R}^d} g(\mathbf{t}) \mathcal{N}(\mathbf{t}|\mathbf{0}, \Sigma) d\mathbf{t} = \int_{[0,1]} g(\Psi(\mathbf{x})) d\mathbf{x} = \int_{[0,1]} f(\mathbf{x}) d\mathbf{x}$$

Importance Sampling with drift α : $\lambda_{IS}(\mathbf{t}) = \mathcal{N}(\mathbf{t}|\alpha, \Sigma)$ for $\alpha = \alpha(\tau j/d)_{j=1}^d$
Choose Ψ_{IS} so that $\lambda_{IS}(\Psi_{IS}(\mathbf{x}))|\Psi'_{IS}(\mathbf{x})| = 1$

$$\mu = \int_{\mathbb{R}^d} g(\Psi_{IS}(\mathbf{x})) \frac{\mathcal{N}(\Psi_{IS}(\mathbf{x})|\mathbf{0}, \Sigma)}{\mathcal{N}(\Psi_{IS}(\mathbf{x})|\alpha, \Sigma)} d\mathbf{x} = \int_{[0,1]^d} g(\Psi_{IS}(\mathbf{x})) \exp(\alpha(\alpha\tau/2 - \Psi_{IS,d}(\mathbf{x}))) d\mathbf{x}$$

Since $\Sigma^{-1}\alpha = (0, 0, \dots, 0, a)^T$

Time Horizon $\tau = 1$; Interest Rate $r = 0$; Volatility $\sigma = 0.5$;
Start Price $S_0 = 100$; Strike Price $K = 200$; Drift $\alpha = 2$



```
>>> sobol = qp.Sobol(dimension=8,seed=7)
>>> params = {
...     "start_price":100,
...     "strike_price":200,
...     "call_put":"call"}
>>> # Without IS
>>> aco = qp.AsianOption(sobol,**params)
>>> _,data = qp.CubQMCSobolG(aco,abs_tol=1e-4).integrate()
>>> # With Drift IS
>>> bmIS = qp.BrownianMotion(sobol,drift=2)
>>> acoIS = qp.AsianOption(bmIS,**params)
>>> _,dataIS = qp.CubQMCSobolG(acoIS,abs_tol=1e-4).integrate()
```

	Time (sec)		Samples	
ϵ	$1e-4$	$1e-5$	$1e-4$	$1e-5$
Without IS	2.7	55.2	2.1e6	3.4e7
With Drift IS	1.1 (42%)	23.7 (42%)	5.2e5 (25%)	8.4e6 (25%)

```
>>> data
```

```
Solution: 0.1759
```

```
BrownianMotion (TrueMeasure Object)
```

```
time_vec      [0.125 0.25 0.375 ... ]
```

```
drift          0
```

```
mean          [0.    0.    0.    ... ]
```

```
covariance    ...
```

```
>>> dataIS
```

```
Solution: 0.1760
```

```
BrownianMotion (TrueMeasure Object)
```

```
time_vec      [0.125 0.25 0.375 ... ]
```

```
drift          0
```

```
mean          [0.    0.    0.    ... ]
```

```
covariance    ...
```

```
transform     BrownianMotion (TrueMeasure Object)
```

```
time_vec      [0.125 0.25 0.375 ... ]
```

```
drift          2^(1)
```

```
mean          [0.25 0.5 0.75 ... ]
```

```
covariance    ...
```


Composed IS

For L composed transforms, let $\Psi_0(\mathbf{x}) = \mathbf{x}$ and define

the first ℓ transforms as $\hat{\Psi}_\ell = (\Psi_\ell \circ \Psi_{\ell-1} \circ \dots \circ \Psi_0)$ and
the complete transform as $\hat{\Psi}_L = (\Psi_L \circ \Psi_{L-1} \circ \dots \circ \Psi_0) = \Psi_{IS}$.

If $\lambda_\ell(\Psi_\ell(\mathbf{x}))|\Psi'_\ell(\mathbf{x})| = 1$ for $\ell = 1, \dots, L$, then

$$\begin{aligned}\mu &= \int_{\mathcal{T}} g(\mathbf{t}) \lambda(\mathbf{t}) \, d\mathbf{t} \\ &= \int_{[0,1]^d} g(\hat{\Psi}_L(\mathbf{x})) \lambda(\hat{\Psi}_L(\mathbf{x})) \prod_{\ell=1}^L |\Psi'_\ell(\hat{\Psi}_{\ell-1}(\mathbf{x}))| \, d\mathbf{x} \\ &= \int_{[0,1]^d} g(\hat{\Psi}_L(\mathbf{x})) \frac{\lambda(\hat{\Psi}_L(\mathbf{x}))}{\prod_{\ell=1}^L \lambda_\ell(\hat{\Psi}_\ell(\mathbf{x}))} \, d\mathbf{x}\end{aligned}$$

Gauss-Kuma Keister IS

Compose

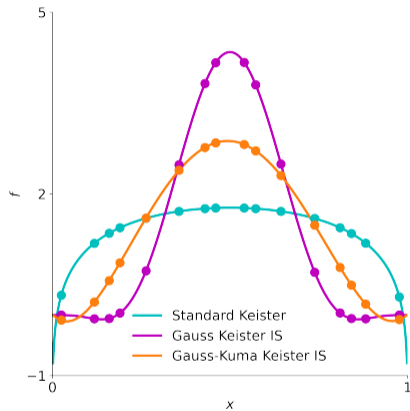
$\Psi_1 : [0, 1]^d \rightarrow [0, 1]^d$, the inverse CDF of Kumaraswamy $\mathcal{K}(\mathbf{a}, \mathbf{b})$, and
 $\Psi_2 : [0, 1]^d \rightarrow \mathbb{R}^d$, the Gaussian $\mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ transform, so that

$$\mathcal{K}(\Psi_1(\mathbf{x})|\mathbf{a}, \mathbf{b})|\Psi_1'(\mathbf{x})| = 1 = \mathcal{N}(\Psi_2(\mathbf{x})|\boldsymbol{\mu}, \boldsymbol{\Sigma})|\Psi_2'(\mathbf{x})|.$$

Then

$$\begin{aligned}\boldsymbol{\mu} &= \int_{\mathbb{R}^d} \pi^{d/2} \cos(\|\mathbf{t}\|) \mathcal{N}(\mathbf{t}, |\mathbf{0}, 1/2) d\mathbf{t} \\ &= \int_{[0,1]^d} \pi^{d/2} \cos(\|(\Psi_2 \circ \Psi_1)(\mathbf{x})\|) \frac{\mathcal{N}((\Psi_2 \circ \Psi_1)(\mathbf{x})|\mathbf{0}, 1/2)}{\mathcal{N}((\Psi_2 \circ \Psi_1)(\mathbf{x})|\boldsymbol{\mu}, \boldsymbol{\Sigma}) \mathcal{K}(\Psi_1(\mathbf{x})|\mathbf{a}, \mathbf{b})} d\mathbf{x}\end{aligned}$$

```
>>> sobol = qp.Sobol(dimension=3,seed=11)
>>> tf1_kuma = qp.Kumaraswamy(
...     sampler = sobol,
...     a = .8,
...     b = .8)
>>> tf2_gauss = qp.Gaussian(
...     sampler = tf1_kuma)
>>> keister_kuma_gauss = qp.Keister(
...     sampler = tf2_gauss)
>>> stop_obj = qp.CubQMCSobolG(
...     integrand = keister_kuma_gauss,
...     abs_tol = 5e-6)
>>> solution,data = stop_obj.integrate()
```



Took 35% the time and 25% the samples compared to standard Keister

```
>>> data
```

```
Solution: 2.1683
```

```
Gaussian (TrueMeasure Object)
```

```
mean          0
```

```
covariance    2(-1)
```

```
decomp_type   pca
```

```
transform     Gaussian (TrueMeasure Object)
```

```
mean          0
```

```
covariance    1
```

```
decomp_type   pca
```

```
transform     Kumaraswamy (TrueMeasure
```

```
      a          0.800
```

```
      b          0.800
```

```
LDTransformData (AccumulateData Object)
```

```
n_total       2(20)
```

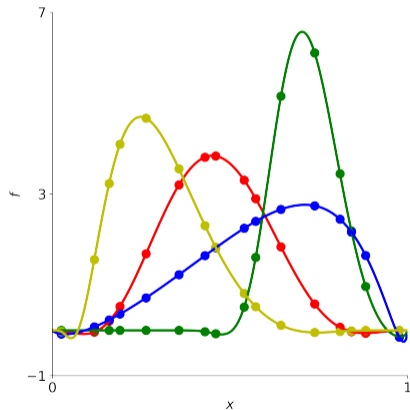
```
solution      2.168
```

```
error_bound   2.25e-06
```

```
time_integrate 1.320
```

QMCPy Resources

- PyPI: pypi.org/project/qmcpy/
- GitHub: github.com/QMCSoftware/QMCSoftware
- Documentation: qmcpy.readthedocs.io
- Blogs: qmcpy.org
- MCQMC2020 Tutorial
 - Slides: qmcpy.org/mcqmc-2020-tutorial/
 - Notebook: tinyurl.com/QMCPyTutorial
 - "Quasi-Monte Carlo Software" Article [5]



References

1. Keister, B. D. Multidimensional Quadrature Algorithms. *Computers in Physics* **10**, 119–122 (1996).
2. Choi, S.-C. T., Hickernell, F. J., McCourt, M. & Sorokin, A. *QMCPy: A quasi-Monte Carlo Python Library*. 2020+. <https://github.com/QMCSoftware/QMCSoftware>.
3. Oliphant, T. *Guide to NumPy*. <https://ecs.wgtn.ac.nz/foswiki/pub/Support/ManualPagesAndDocumentation/numpybook.pdf> (Trelgol Publishing USA, 2006).
4. Hickernell, F. J. & Jiménez Rugama, L. A. *Reliable Adaptive Cubature Using Digital Sequences*. 2014. arXiv: [1410.8615](https://arxiv.org/abs/1410.8615) [math.NA].
5. Choi, S.-C. T., Hickernell, F. J., Jagadeeswaran, R., McCourt, M. J. & Sorokin, A. G. *Quasi-Monte Carlo Software*. 2021. arXiv: [2102.07833](https://arxiv.org/abs/2102.07833) [cs.MS].